## Geometry–Topology Prelim, Fall 2012

**1.** For which values of the constant c is the level set  $x^2 + y^2 - zw = c$  a submanifold of  $\mathbb{R}^4$ ?

**2.** Consider the vector field  $v = \sum_{i} x_i \frac{\partial}{\partial x_i}$  on  $\mathbb{R}^n$ .

- (a) Find the flow of v.
- (b) Prove that the only one-form on  $\mathbb{R}^n$  invariant under the flow of v is the trivial one-form  $\alpha = 0$ .

**3.** Recall that the fundamental group  $\pi_1(X, x_0)$  is the set of homotopy classes of base point preserving maps  $(S^1, s_0) \to (X, x_0)$ . Let  $[S^1, X]$  be the set of free homotopy classes of maps without conditions on base points. Then there exists a map  $\Phi: \pi_1(X, x_0) \to [S^1, X]$  obtained by ignoring base points.

- (a) Show that  $\Phi$  is onto if X is path connected.
- (b)  $\Phi([f]) = \Phi([g])$  if and only if [f] and [g] are conjugate in  $\pi_1(X, x_0)$ .
- (c) Let X be the one point union of two real projective planes  $X = \mathbb{R}P^2 \vee \mathbb{R}P^2$  joined at a point  $x_0$ . Compute  $\pi_1(X, x_0)$ . (You can use the fact that  $\pi_1(\mathbb{R}P^2) = \mathbb{Z}_2$ .)
- (d) Determine the set of free homotopy classes of maps  $[S^1, X]$ .

**4.** Let  $f: S^n \to S^n$  be a continuous map. Assume that f is fixed point free, i.e.,  $f(x) \neq x$  for all  $x \in S^n$ .

- (a) Show that f is homotopic to the antipodal map.
- (b) Assume that n is even. Show that there exists a point such that f(x) = -x.
- (c) Show that for any odd n there exists a continuous map  $f: S^n \to S^n$  such that  $f(x) \neq x$  and  $f(x) \neq -x$  for all x. (Hence the condition that n is even is essential in (b).)
- 5.
- (a) Find the Gaussian and mean curvature of the surface z = x y with the Riemannian structure induced by the standard Euclidean structure on  $\mathbb{R}^3$ .
- (b) If M is a surface in  $\mathbb{R}^3$ , then a Euclidean isometry  $\varphi$  of  $\mathbb{R}^3$  such that  $\varphi(M) = M$  is called a *Euclidean symmetry of* M. Show that every Euclidean symmetry of the surface z = x y is an orthogonal transformation, i.e., a linear transformation preserving the Euclidean inner product on  $\mathbb{R}^3$ .
- (c) Determine which orthogonal transformations are Euclidean symmetries of the surface z = x y.