

Geometry Topology Prelim: Winter 2017

[1] True or False? 'If X and Y are smooth vector fields on a manifold and p is a point of the manifold and $X(p) = 0$ and $Y(p) = 0$, then $[X, Y](p) = 0$.' Give a proof or counterexample according to your answer.

[2] Let $F: X \rightarrow Y$ be an (onto) submersion such that Y is connected and for every point $y \in Y$ the inverse image $F^{-1}(y)$ is connected.

(1) Prove that X is connected.

(2) Is the converse true? If X is connected must all inverse images be connected?

[3] Consider the distribution

$$\text{Ker}(x dx + y dy + v du + u dv) \cap \text{Ker}(x dx + u du + v dv)$$

on the subset $y \neq 0$ of \mathbb{R}^4 with coordinates (x, y, u, v) . Is this distribution involutive?

[4] Consider an annulus. Identify antipodal points along the outer circle, and also identify antipodal points along the inner circle. Calculate the fundamental group of this identification space X . Is this space X a compact topological manifold? If not, prove it. If yes, identify this space among the surfaces appearing in the classification theory.

[5] (1) Consider a unit square $I = \{(x, y) \in \mathbb{R}^2 \mid 0 \leq x, y \leq 1\}$. Identify the opposite edges by translation. Calculate the homology of the resulting surface.

(2) Consider a 3-dimensional unit cube $K = \{(x, y, z) \in \mathbb{R}^3 \mid 0 \leq x, y, z \leq 1\}$. Identify opposite faces by translation. Calculate the homology of the resulting 3-dimensional manifold.

[6] Consider the upper half plane with standard hyperbolic metric $g = \frac{dx^2 + dy^2}{y^2}$. Give the coordinate formula for the gradient ∇f of a function $f(x, y)$ with respect to this metric.

[7] Suppose that (M, g) is a Riemannian manifold.

(1) Define the exponential map.

(2) Prove that the differential of the exponential map at the origin of the tangent space at a point is the identity.