## GEOMETRY AND TOPOLOGY PRELIMINARY EXAM

## Winter 2019

[1] Let [x; y; z; w] be homogeneous coordinates in  $\mathbb{R}P^3$  and consider the subset X defined by the homogeneous polynomial equation

$$x^2 + y^2 - z^2 = 0$$

Prove that X is a smooth manifold except at one (singular) point. Can you describe the shape of X qualitatively?

[2] Identify  $\mathbb{R}^2$  with coordinates (x, y) with  $\mathbb{C}$ , with coordinate z = x + iy. Likewise, identify a copy of  $\mathbb{R}^2$  with coordinates u, v with  $\mathbb{C}$  with coordinate w = u + iv. Let a function  $f : \mathbb{R}^2 \setminus \{(1,0), (-1,0)\} \longrightarrow \mathbb{R}^2$  be given by

$$f(z) = \frac{1}{z-1} - \frac{1}{\overline{z}+1}.$$

- (1) Show that f extends to a smooth map  $\overline{f}: S^2 \to S^2$ , where  $S^2$  (or  $\mathbb{C}P^1$ ) is the one-point compactification of  $\mathbb{R}^2$  (or  $\mathbb{C}$ ).
- (2) Compute the degree of f.

[3] Let  $\mathbb{R}^2$  be parametrized by (u, v), and let  $\mathbb{R}^3$  be parametrized by (x, y, z). In  $\mathbb{R}^2$ , let  $U = (0, \pi) \times (0, 2\pi)$ , and let  $f : \mathbb{R}^2 \to \mathbb{R}^3$  be given by

$$f(u,v) = \left(\sin(u)\cos(v), \sin(u)\sin(v), \cos(u)\right)$$

- (1) Compute  $f^*(x), f^*(y)f^*(z), f^*(dx), f^*(dy)$  and  $f^*(dz)$ .
- (2) Consider the differential form  $\omega = xdy \wedge dz + ydz \wedge dx + zdx \wedge dy$  on  $\mathbb{R}^3$ . Compute  $\int_U f^*(\omega)$ .

[4] Consider a vector field in  $\mathbb{R}^2$  whose value at  $x \in \mathbb{R}^2$  is

$$V(x) = v_1(x)\frac{\partial}{\partial x_1} + v_2(x)\frac{\partial}{\partial x_2}$$

for  $v_i$  smooth functions, and let  $f_1, f_2$  be smooth functions  $\mathbb{R} \to \mathbb{R}$ .

- (1) Calculate the Lie derivative  $\mathcal{L}_V\left(f_1(x_1)dx_1 \otimes \frac{\partial}{\partial x_1} + f_2(x_2)dx_2 \otimes \frac{\partial}{\partial x_2}\right)$  and find the condition on  $f_1, f_2$  arising from the constraint  $\mathcal{L}_V = 0$ .
- (2) Calculate the Lie derivative  $\mathcal{L}_V(f_1(x_1)dx_1 \otimes dx_1 + f_2(x_2)dx_2 \otimes dx_2)$  and find the condition on  $f_1, f_2$  arising from the constraint  $\mathcal{L}_V = 0$ . How does this compare with the condition from the previous problem?

[5] Let  $T = S^1 \times S^1$  be a torus with a base point  $(x_0, y_0)$ . Let  $X = \mathbb{R}P^2 \cup T$  be a space obtained by identifying  $\mathbb{R}P^1 \subset \mathbb{R}P^2$  with  $S^1 \times \{y_0\} \subset T$ .

- (1) Compute the fundamental group of X.
- (2) Let T' be a punctured torus, that is, T' is T minus one point  $p \notin \mathbb{R}P^1$ . Let  $X' = \mathbb{R}P^2 \cup T'$  be the space obtained by a similar construction. What is the fundamental group of X'?

[6] Let  $D^3$  be the 3-dimensional closed unit ball. Let  $f: D^3 \to D^3$  be a continuous map. Show that f has a fixed point.

[7] Let M be the boundary of a compact (not necessarily convex) polyhedron in  $\mathbb{R}^3$  (with straight edges and flat faces). At each vertex v of M, define its vertex angle defect d(v) by

$$d(v) = 2\pi - \sum (\text{face angles at } v),$$

where the summation runs over all faces incident to the vertex v, and by "face angle" we mean the angle at v within each incident face. Prove the following discrete version of Gauß-Bonnet Theorem.

$$\sum_{v} d(v) = 2\pi\chi(M).$$